Stakeholder Needs

1. The robotic hand should have a morphology similar to the human hand.
2. The robotic hand should copy the pose and motion of the hand and replicate it.
3. The replication of the hand motion should be continuous and happen in real time.
4. The robotic hand should be roughly equal in size to the human hand.
5. The robotic hand should be mobile, can be easily moved from place to place.
6. The system should be powered from regular power outlet and mobile battery.
7. The robotic hand should be physically separated from the operator’s hand.
8. Lag in the robot response should be less than the human eye can notice.